

Elliptical Parallel axiom

For every line l and every point P not on l , there is no line m so that P is on m and $m \parallel l$.

Euclidean Parallel axiom

For every line l and every point P not on l , there is exactly one line m so that P is on m and $m \parallel l$.

Hyperbolic Parallel axiom

For every line l and every point P not on l , there are at least two lines m and n so that P is on both m and n , and both m and n are parallel to l .

Def: Let S be a nonempty set. ~~and~~ A transformation group is a collection of transformations on S so that:

- ① the identity transformation is in G ;
- ② all transformations in G are invertible, and their inverses are in G .
- ③ G is closed under composition.

Def: Let S be a non-empty set and G a transformation group on S . The pair (S, G) is called a model of a geometry or a geometry, the set S is the underlying space of the geometry, and the collection G is transformation group of the geometry.

Def: Let (S, G) be a geometry. If $A \subseteq S$, then we say that A is a figure of the geometry.

Def: Two figures A and B of a geometry (S, G) are congruent if there is a transformation $T \in G$ so that

$$T(A) = B.$$

$$T(A) = \{Tz : z \in A\}.$$

eg Recall: Special Euclidean transformations are rotations and translations.

Euclidean transformations are rotations, translations, and reflections.

Let E_S be the collection of all Special Euclidean transformations and their compositions.

Let E be the collection of all Euclidean transformations and their compositions.

Eg (\mathcal{L}, E_s) is a geometry called the Special Euclidean geometry.

(\mathcal{L}, E) is a geometry called euclidean geometry.

Def: Let (S, G) be a geometry, and D a set of figures in the geometry.

The set D is invariant if for every $A \in D$ and transformation $T \in G$,
 $T(A) \in D$.

A function f defined on D is invariant if for every figure $B \in D$ and every transformation $T \in G$, $f(B) = f(T(B))$.

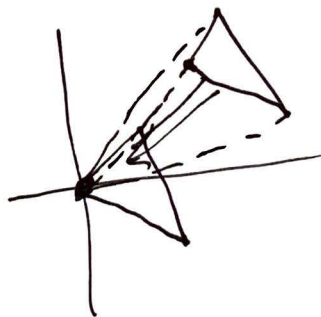
Def: Let $\triangle ABC$ be a triangle. The perimeter of $\triangle ABC$ is $AB + BC + AC$.

Eg] Let D be the collection of all triangles in (\mathbb{C}, E) .

Define $p: D \rightarrow \mathbb{R}$ by $p(\Delta) =$ the
perimeter of
 Δ .

p is an invariant function of
 (\mathbb{C}, E) .

Define $p': D \rightarrow \mathbb{R}$ by $p'(\Delta)$ is the
sum of the distances of each vertex
of Δ to the origin.



p' is not invariant in (\mathbb{C}, E) .

Def: Two geometries (S_1, G_1) and (S_2, G_2) are isomorphic if there is a continuous invertible function $f: S_1 \rightarrow S_2$ so that

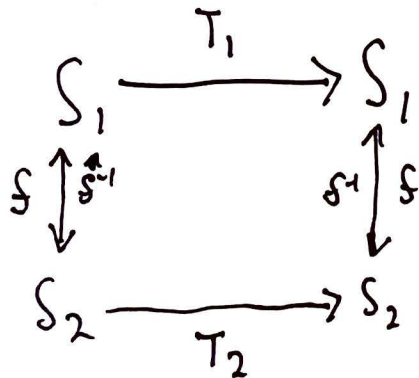
① for every $T_1 \in G_1$ there is a corresponding $T_2 \in G_2$ so that

$$T_1 = f^{-1} \circ T_2 \circ f$$

② for every $T_2' \in G_2$ there is a corresponding $T_1' \in G_1$ so that

$$T_2' = f \circ T_1' \circ f^{-1}$$

The function f is called an isomorphism.



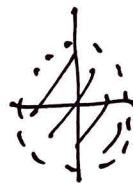
Def: The closed unit disk is

$$D = \{z : |z| \leq 1\}$$



The open unit disk is

$$D^\circ = \{z : |z| < 1\}$$



eg] Define $f: \mathbb{C} \rightarrow D^\circ$ by

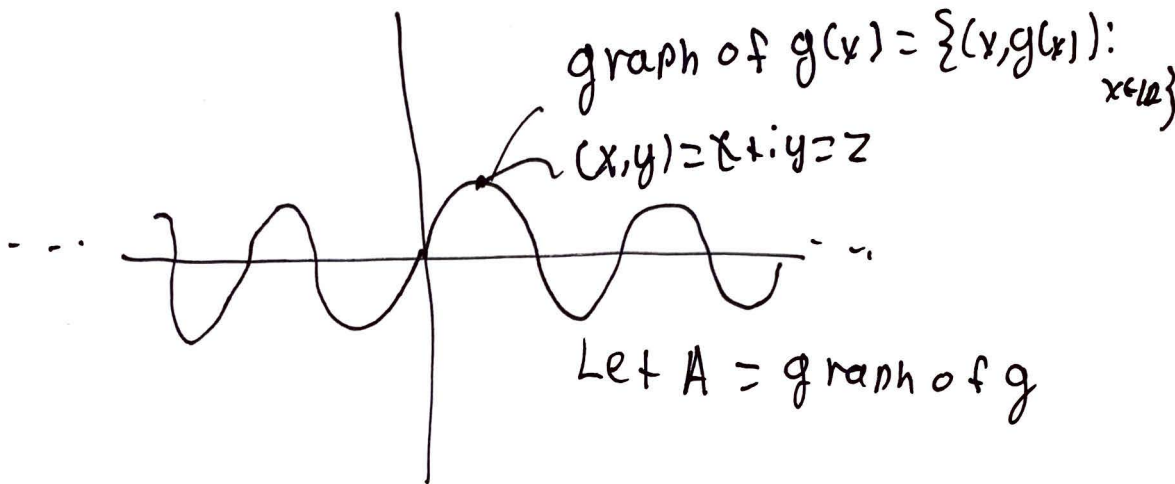
$$f(z) = \frac{z}{\sqrt{1+|z|^2}}$$

f is continuous and invertible. So

an isomorphism exists between

(\mathbb{C}, E) and (D°, E') .

$$g(x) = \sin(10x)$$



$f(A)$

